

# Zhiqiang Fu 付志强

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## EDUCATION BACKGROUND

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09/2014 – 06/2018 **B.S. in Mechatronics Engineering, Zhejiang University (ZJU) | Graduated in 06/2018**

College of Mechanical Engineering & Chu Kochen Honors College

**GPA:** 3.93/4.00, 90.36/100; **Ranking:** Top 2% among 128 students

## RESEARCH PROJECT

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### **Mechanical Design and Finite Element Analysis of a New Wearable Cuffless Blood Pressure Monitoring**

*Massachusetts General Hospital / Harvard Medical School | Student Intern | 09/2017-05/2018*

- Developed wearable technology for physiological signal monitoring.
- Designed a new mechanical structure of BP-Glass and conducted finite element analysis (FEA) to build bio-signal model for superficial tonometry artery (STA).

### **Temporal Focusing for Material Processing on Curved Surfaces**

*The Chinese University of Hong Kong | Research Assistant | 07/2017-08/2017*

- Developed a wavefront shaping system to engineer the shape of light sheet of a femtosecond laser temporal focusing fabrication system.
- Developed the algorithm for arbitrary beam shaping via Lee Hologram using Matlab.

### **Electromechanical Actuation and Control of Soft Robotic Fish with Multiple Degrees of Freedom**

*ZJU | Project Leader | 09/2016-07/2017*

- Designed a novel, soft fish based on Dielectric Elastomer (DE) that moves freely in the water, such as floating up sinking down, stabilizing at a designated depth, moving forward fast and rotating within a small radius.

### **A Novel Data Glove Based on the Film of Carbon Nanotube**

*ZJU | Project Leader | 03/2017-04/2017*

- Fabricated the glove by mixing the carbon nanotubes, PDMS and the curing agent, then painting it on a membrane of dielectric elastomer.
- Implemented machine learning algorithms to recognize and classify the gestures of the fingers.

### **Electromechanical Control and Stability Analysis of a Soft Swim-Bladder Robot Driven by Dielectric Elastomer**

*ZJU | Project Member | 09/2016-03/2017*

- Designed and constructed the soft swim-bladder robot.
- Adopted an on-off control strategy to maintain the position of the robot at a designated depth in water.

### **A Real-time Pre-impact Fall Detection and Protection System**

*ZJU | Project Member | 05/2016-04/2017*

- Designed an enhanced inertial filter to reduce the drift of velocity integrated from vertical acceleration.
- Conducted experiments to distinguish falls from daily activities such as jogs and jump.

